

SYNTHETIC GRIPPER RRMG



Your customized gripper solution for sensitive workpieces with complex geometries



RRMG SYNTHETIC GRIPPER

Whether round profiles, prismatic workpieces or free-form surfaces, the synthetic gripper RRMG from RÖHM is individually adapted to your workpiece and produced for you. It only needs a 3D-model of the workpiece and RÖHM is developing and producing your individual synthetic gripper RRMG. This customized solution is perfect for gripping and clamping sensitive workpieces with complex geometries.

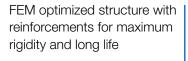
30 % HIGHER GRIPPING FORCE

- Secure gripping and clamping of larger workpieces by 30 % higher clamping force

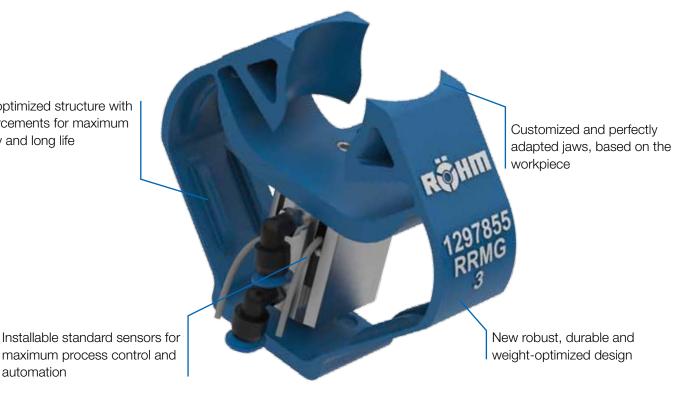
MAXIMUM PROCESS RELIABILITY

- ⊕ Up to 16 million gripping cycles without maintenance or wear and tear

OPTIMIZED DESIGN



automation





OPTIMIZED DESIGN

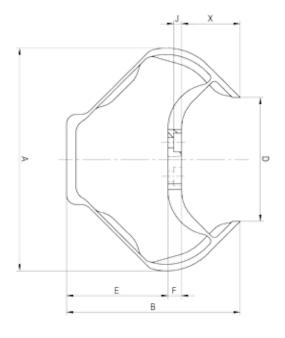
The especially robust and durable design of new synthetic gripper RRMG allows 30 % higher clamping force and enables secure gripping and clamping of even larger workpieces.

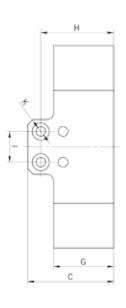


INDIVIDUAL UNIQUE PIECE

By using the 3D-model of the workpiece, the synthetic gripper RRMG is customized and perfectly adapted to the part to grip. Special jaws with free-form surfaces allow secure gripping and clamping of sensitive workpieces with complex geometries.







Synthetic gripper RRMG

Syntholic gripper in livid															
	Size	Gripping force (N)*	Hub (mm)*	Gripping point X	Α	В	С	D	E	F	G	Н	1	J	ΚØ
RRMG	2	80	2,6	23,2	92	75,8	37	50	47	5,5	25	31	13	3,4	4,5
RRMG	3	152	4,3	31,2	118,6	92,4	50	66	54	7,2	35	42,5	18	4,2	5,5

^{*} at gripping point X.



RÖHM GmbH

Heinrich-Röhm-Straße 50 89567 Sontheim/Brenz Germany Tel +49 7325 16 0 Fax +49 7325 16 510 info@roehm.biz www.roehm.biz

